

# Instrumentation for In Situ Analysis Missions III: Rock Core and Caching Technique

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Thomas Myrick, Chief Engineer

tmyrick@bearmechanisms.com

### Overview of In Situ Tool

- Drill (4 motors)
- Drill bit & holder (Zero actuators)
- Surface abrasion bit & holder (Zero actuators)
- Cache and sealing system (zero actuators)

No additional motors needed beyond the drill



### Science Requirements

- Ability to deploy the corer to a wide range of targets away from the rover body, and against rover hazards
- Ability to drill into loose rocks, rock outcrops, and collect multiple rocky samples
- Collect granular material (regolith) and move them into a sample cache
- Sample caching and preservation
- Choose between samples replace with higher value samples, take sacrificial samples, or deposit samples on Martian surface for later retrieval.
- Bit change-out
- Surface Abrasion Tool



### Bear Drill Capabilities

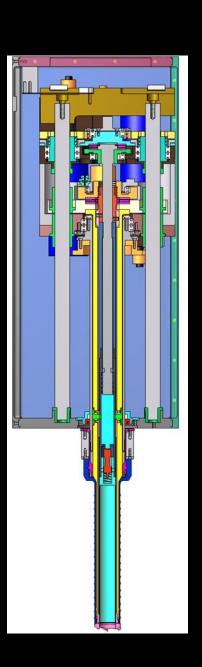
- Lower risk of core damage
- Lower risk of core becoming stuck in the drill
- Accepts sample Tubes
- Flexibility of system-easy to provide "add-on" capability with no impact to design
- Simplicity of design



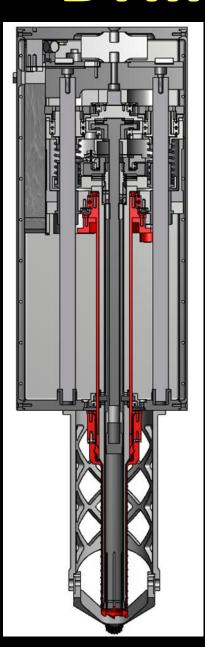


### The Drill



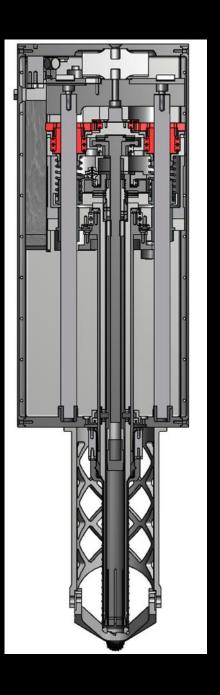


### Drill Axes



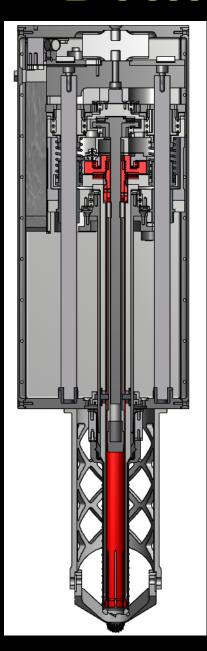
Drill

**Z-Axis** 

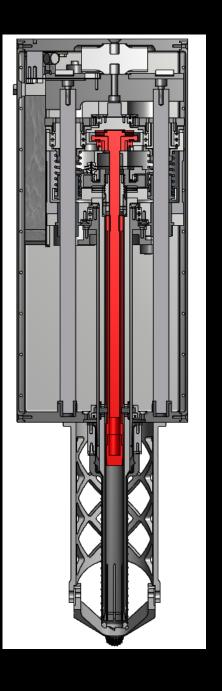




### Drill Axes



Push Rod



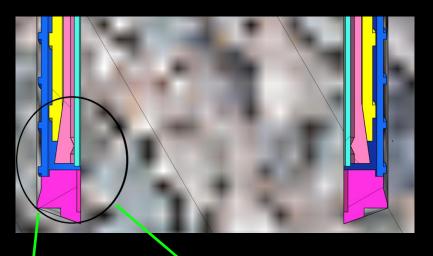


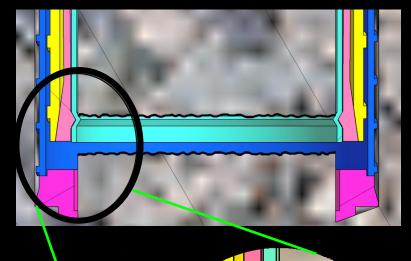
**Break Off** 

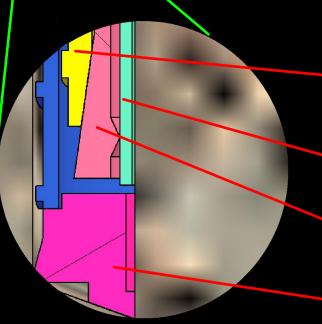
# Cross Section of Drill Tip

Un-broken core

Broken core and crimped sample tube





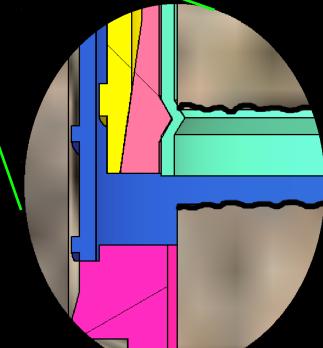


**Ground Tube** 

Sample Tube

Collet Tube

**Drill Bit** 



### Collet Tube

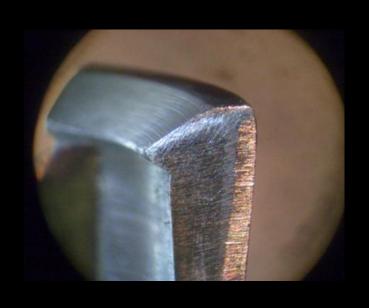
#### The Central Element of the Design

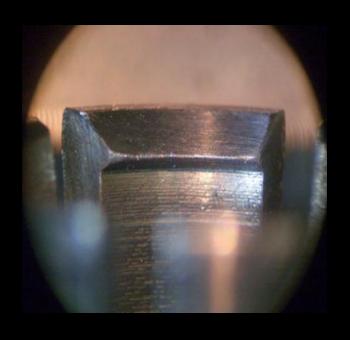


- Collet does not rotate with respect to core
- Collet fingers move inward/upward to break core
- Secures the core within the sample tube
- Rigidly and concentrically holds other tools
- Sensors confirm core break



### Inner Teeth of Collet Tube









### Choose Between Samples

- A version of the sample tube can hold granular material (regolith)
- In absence of sample tube, a core can still be acquired, ejected and studied in situ
- Samples can be ejected onto the Martian surface for later pick up
- Samples can be replaced with higher value samples





# Sample Tube/Crimp Test





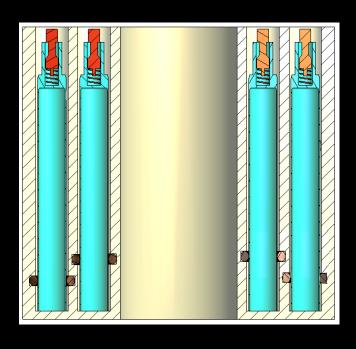


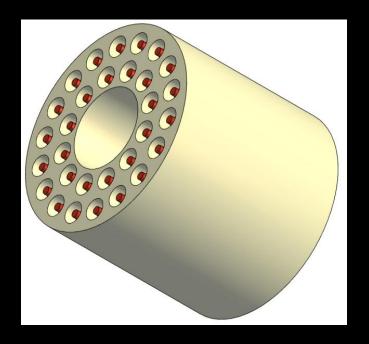




### Sample Cache

#### Cross section of Cache

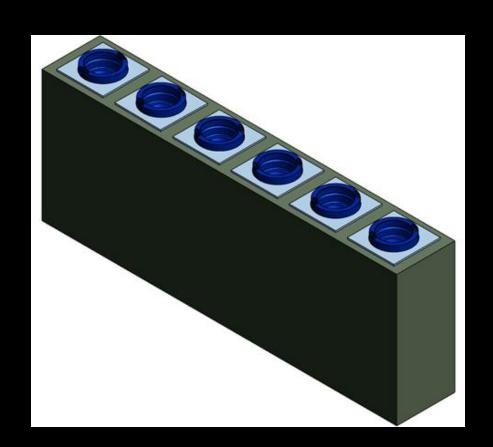




 No sample tube caps required; cache itself acts as a cap that seals each sample tube throughout the mission

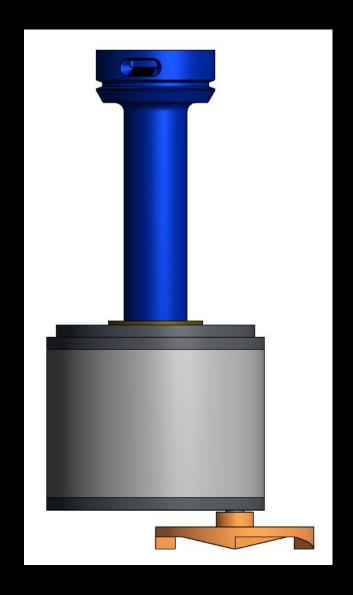


### Drill Bit Holder





### Surface Abrasion Tool





# Summary Future Science Drill

- Must be low risk
- Ability to inspect, eject or save sample
- Flexibility of system-easy to provide "add-on" tools with no impact to design
- Simplicity of design No additional motors-
- Versatility makes technology mission adaptable



